REDWALL® INSTALLATION INSTRUCTIONS

NO.59-1576-1 0905-30



FEATURES

- * Low power consumption (3-9VDC, 40µA (standby) 5mA max.)
- Low battery signal
- Intelligent PIR Detection System
- Three dual pyro-elements with patented Double Conductive Shielding
- Detection of ambient temperature and illuminance for automatic sensitivity management
- Advanced detection algorithm
- * Anti-vandalism functions
 - Max.4 m (13 ft.) installation height
 - Anti-rotation function with accelerometer
 - Anti-masking function with photo-beam
- * Independent sensitivity selector for near/far areas
- Detection logic selector
- Detection range selector
- Independent N.C. and N.O. ALARM output
- Adjustable alarm interval time
- Reinforced polycarbonate housing

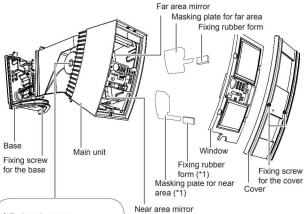
REDWALL-V



: Low current Synthesized Intelligent PIR

- SIP-3020WF
- SIP-4010WF
- SIP-404WF

PARTS IDENTIFICATION



Adjustment screws (two facing each other) Angle adjustment guide Fixing screw

*1: Not used for the SIP-4010WF and SIP-404WF

INSTALLATION AND MAINTENANCE NOTES

Hold the main unit securely when you install or service it. If you remove your hands from the main unit when cables are connected to it, the main unit may fall and the connector cables may break Never repair or modify product or the circuit board may be damaged. Verify that the power is off before connecting the Nylon wire wiring. loop

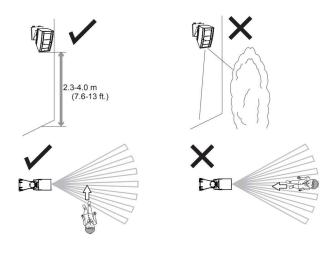
INSTALLATION HINTS

When servicing, the sensor

can be hooked onto the

loop.

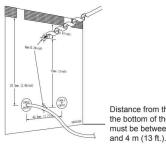
base using the nylon wire



Mount the detector so that the majority of traffic flow is across the detection pattern.

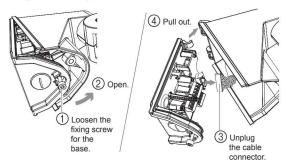
Wall Mounting

(1) Attach the paper template (an accessory) onto the wall, and drill a 6-mm dia. mounting hole and a cabling hole. Insert the anchor bolt (an accessory) into the board mount hole.

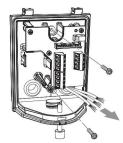


Distance from the ground to the bottom of the template must be between 2.3 m (7.6 ft.)

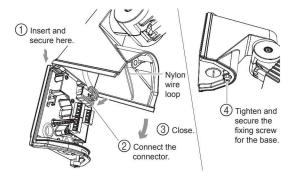
(2) Using an allen key, remove the main unit from the base.



(3) Drill through the bushing of the wiring hole, pass the cable through the hole, and secure the base to the wall.



- (4) Connect the cable to the terminal block (see Step 3-3).
- (5) Mount the main unit onto the base.



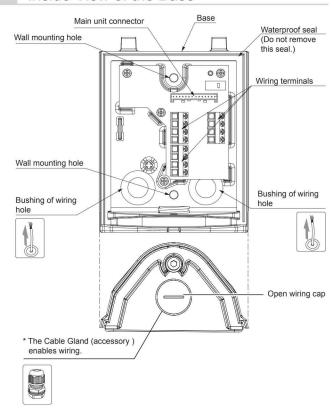
When mounting the main unit, take care not to trap the nylon wire loop. Also, take care not to get your fingers caught.

(6) Check to see that the various settings and operations are

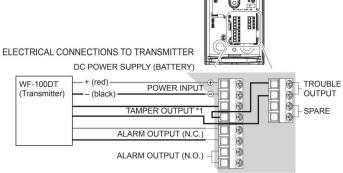
Caution>>

When the red LED flashes after the power turns on, this signifies that the system is warming up. Wait for approximately 120 seconds.

Inside View of the Base



WIRING



*1: TAMPER terminals to be connected to a 24 hour supervisory loop

Cautions>>

Maximum wiring length is 3 m.

Name	Function			
TROUBLE OUTPUT	Trouble out is used for anti-masking signal and low battery signal. When an object is placed close to the lens surface, for a period of more than 120 seconds (approx.), the IR anti-masking circuit will activate and generate a trouble signal. When the battery power is less than 2.3V DC, and this condition continues more than 2.5 hours, the signal will be generated.			
	It is detected when the cover is opened.			
	It is detected when the main unit is removed from its base.			
TAMPER OUTPUT	Anti-Rotation: Damage sustained by the main unit is detected. If the main unit is impacted in a horizontal or vertical direction and if the position of the main unit has changed, damage sustained by the main unit will be detected.			

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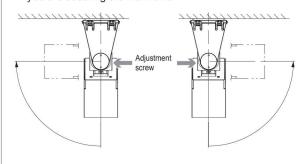
DETECTION AREA SETTING

You can adjust the detection area by 90 degrees in a horizontal direction and by 10 degrees in a vertical direction. Correct the vertical detection angle according to the mounting height of the sensor unit.

Applicable models SIP-3020WF SIP-4010WF SIP-404WF

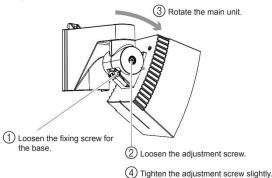
Cautions>>

To rotate the main unit counterclockwise, loosen the RHside adjustment screw. To rotate the main unit clockwise, loosen the LH-side adjustment screw. Otherwise, you may find it difficult to tighten or you may find that you cannot tighten the adjustment screw when you are securing the main unit.

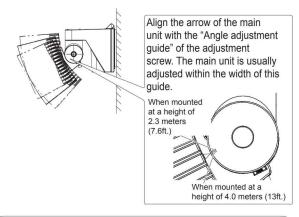


To rotate the unit counterclockwise
To rotate the unit clockwise

(1) Adjust the angle of the main unit in a horizontal direction so that you can cover the desired detection area.



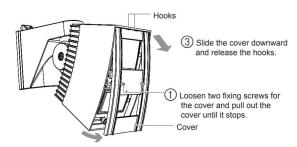
(2) Adjust the angle of the main unit in a vertical direction so that you can cover the desired detection area.



Cautions>>

If the mounting wall is at an angle, the arrow of the main unit may exceed the top or bottom limit of "Angle adjustment guide". Always check this using the area viewfinder or the walk tester. If the detection area is too high or too low, an object outside the detection area may be detected or incorrect object detection may occur.

(3) Remove the cover.

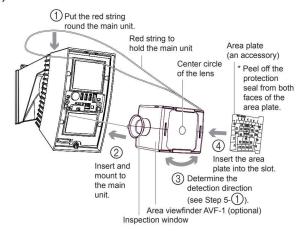


② Hold the heads of both cover fixing screws with your hands, and pull down and remove the bottom section of the cover from the main unit.

Cautions>>

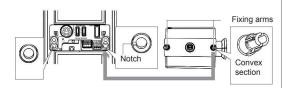
The cover is linked to the main unit by nylon wire loop so that the cover does not fall. Do not pull the cover using excessive force.

(4) Mount the area viewfinder.

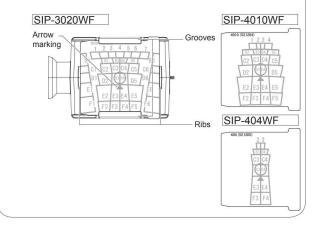


Mounting tips>>

 Engage the convex section of the area viewfinder fixing arms with the notches of the main unit, and insert and mount the arms

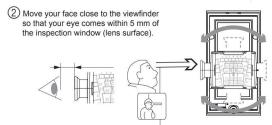


- Mount the area plate so that an arrow of the plate center section faces upward and the letter surface can be seen.
- Insert the area plate into the top and bottom grooves of the area viewfinder until the plate is stopped by the ribs.



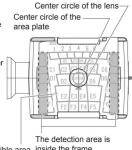
(5) Fine adjust the main unit angle in vertical and horizontal direction by observing the target area through the area viewfinder.

> To change the direction of the inspection window, rotate the area viewfinder in a horizontal direction until it clicks and stops



- (3) Locate the center circle of the area plate on the center circle of the lens of the area viewfinder, and check the detection area pattern on the area plate and the background image.

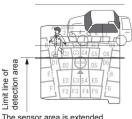
 * Each letter on the area plate
 - corresponds to each mirror number (see Step 8-2).
 - You cannot observe mirror numbers B1 to F1 and B6 to F6 (shown at right) of the SIP-3020 area plate through the inspection window. Check them using the walk tester.



Invisible area inside the frame border.

Adiustina tips>>

If you experience any of the following, see Step 10.



over the street where a person

walks or a car drives

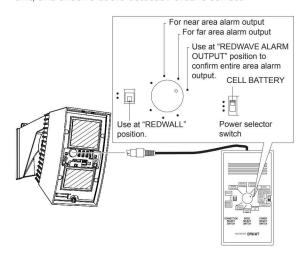




Branches of a tree and grass move when the wind blows.

Cautions>>

- The area viewfinder is a supporting tool for detection area adjustment.
- After you have adjusted the detection area using the area viewfinder, always check the area using the walk tester.
- Never look directly into the sun through the area view finder
- After you have used the area viewfinder, store it away from direct sunlight.
- (6) Securely tighten the adjustment screw that you have loosened.
- (7) Connect the walk tester OPM-WT (optional) to the sensor unit, and check that the detection area is correct.



- ① When the power selector switch is turned to "CELL BATTERY" position after plugging the cable into the walk tester connector, a continuous beeping sound will be heard.
- ② When a pedestrian first enters the detection area, the strong and weak beeps will sound alternately.
- ③ When the entirety of a pedestrian's body is detected, the strong beep will sound continuously.

Cautions>>

 OPM-WT can not be operated at the "Power supply from sensor" position of the power select switch.

Cautions>>

When you are checking the detection area, take care not to cover the shaded area of the window with the walk tester or its cable. If infrared beams to the sensor are partially shielded, the detection sensitivity will drop and the detection operation may fail.

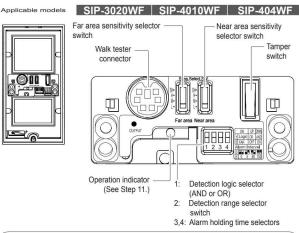
If it is difficult to detect an object>>

- 1. Set the detection logic switch to the "OR" position (see Step 5-2).
 - If the sensor is OK when you have completed the walk test, return the logic switch to the "AND" position.
- 2. Adjust the sensor sensitivity switch (see Step 5-1).

To mask the detection area>>

Detection area	How to mask the area	Reference	
	Use the switch.	5-3	
Far area	Use the masking plate (mounted in the main unit).	Step 7	
Near area	Use the masking plate (mounted in the main unit).	8-1	
	Attach the masking seal (an accessory) to the area mirror surface.	8-2	

5 **FUNCTION SETTING**



Cautions>>

If the red LED keeps blinking for approx. 120 seconds after turning the power on, turn the power off and then on again.

Sensitivity Selector Switch for Near and Far Area

Applicable models

SIP-3020WF SIP-4010WF SIP-404WF

You can change the sensitivity for far area detection and near area detection independently.



SELECTOR POSITION	FUNCTION
SH	Suitable for sites requiring a level of sensitivity higher than "H"
Н	Suitable for sites requiring a level of sensitivity higher than "M"
M (Factory default)	Suitable for standard applications
L	Suitable for hostile and narrow area

Detection Logic Selector Switch

Dip switch 1

SIP-3020WF | SIP-4010WF | SIP-404WF

The near area sensor has two dual-element devices, and it covers two types of plane areas alternately using the two devices.

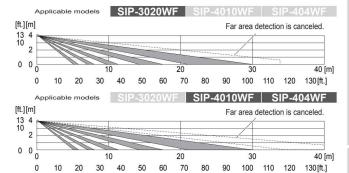
ON	UP
	↓ DWN
1234	אואטטו

	SELECTOR POSITION	STATUS	FUNCTION	
N	UP	OR (Factory) default)	A sensor signal is output when an object is detected in either of the two detection areas. * Use this mode when you adjust the detection area. Switch to AND mode after you have finished the detection area adjustment.	
	DWN	AND	Use this mode to reduce instances of incorrect detection of objects. The sensor signal is output only when an object is detected within the two detection areas. If any objects are blocking multiple detection areas, use OR mode.	

Detection Range Selector Switch Dip switch 2

ON	UP
1 2 3	DWN

	SELECTOR POSITION	STATUS	FUNCTION		
١	UP	OFF	Cancels the far area detection. The detection area is reduced as shown below.		
	DWN	ON (Factory) default)	Enables the far area detection.		



Cautions>>

If you cancel the far area detection, the detection distance is limited to approximately 20 meters (65ft.). Be sure to readjust and check the detection area using the area viewfinder and the walk tester.

Alarm Interval Switch

Dip switch 3-4

Applicable models SIP-3020WF SIP-4010WF SIP-404WF

You can set an interval (4 different times) to suspend the alarm signal output.

For example, if you set this interval to 60 seconds, no more alarm signals will be output for 60 seconds after the output of the first alarm signal. It works to avoid frequent outputs to save battery life. If no pedestrians are detected for more than 60 seconds, the system returns to the standby mode.

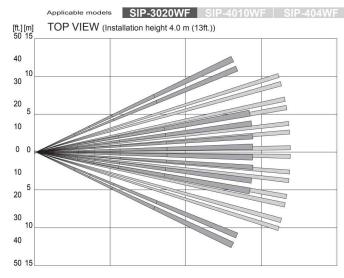
Then, when a pedestrian is detected, the alarm signal will be output.

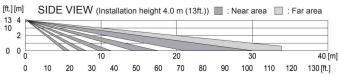
SELECTOR POSITION	ON	ON	ON	ON
	1 2 3 4	1 2 3 4	1 2 3 4	1 2 3 4
FUNCTION	0 sec (Factory default)	5 sec	60 sec	150 sec

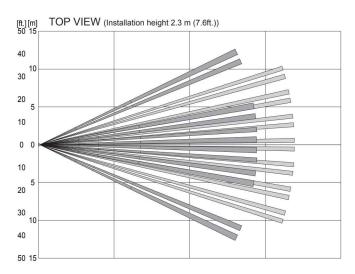
Cautions>>

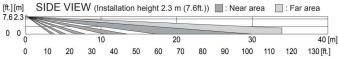
The alarm interval is set to 0 sec as a factory default to allow the detection area to be correctly recognized for the Walk-test. Set the alarm interval switch after adjusting the detection area

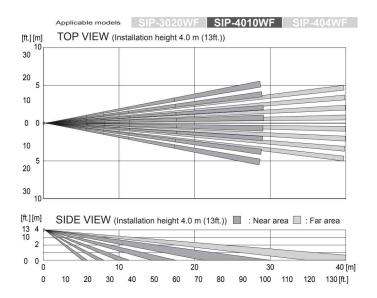
6 DETECTION AREA

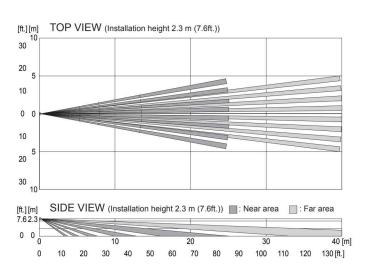


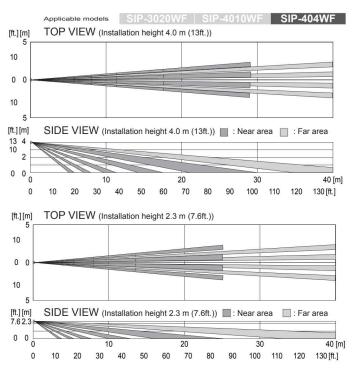












MASKING THE FAR AREA SENSOR

The far area mirror mounted in the main unit has 2 far masking plates; one at the right side of this mirror and the other at the left side of this mirror. You can mask the detection area by changing the position of these masking plates.

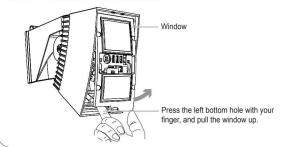
Cautions>>

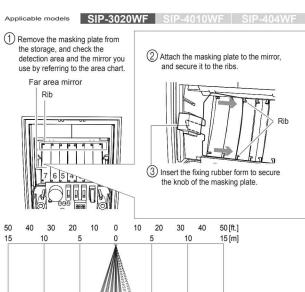
- You can only mask the detection area from its outside to its inside using the masking plates. You cannot mask only the inside detection area.
- However, if you need to mask the inside detection area only, use the white space (margin) of the near area masking seal (an accessory) for the masking. Attach the seal and mask all mirrors that you need to shield.

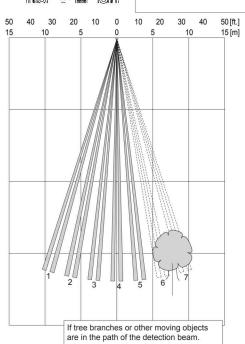
Cautions>>

- The window is linked to the main unit by nylon wire loop so that the window does not fall. Do not pull the window using excessive force.
- After you have masked the detection areas, mount the window and place the excessive nylon wire loop inside the main unit.

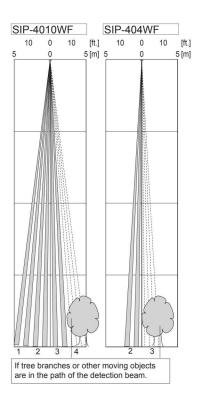
How to remove the window>>







Applicable models SIP-3020WF SIP-4010WF SIP-404WF 1 Remove the masking plate from the storage, and check the detection area and the mirror you use by referring to the area chart. Far area mirror Rib 3 Insert the fixing rubber form to secure the knob of the masking plate.



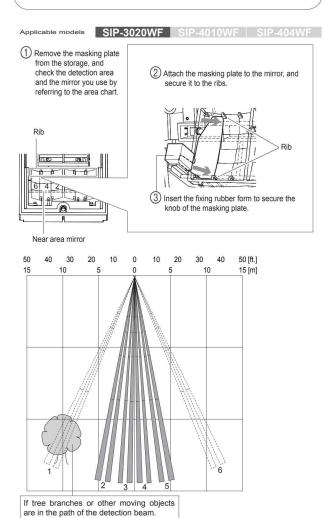
MASKING THE NEAR AREA SENSOR

8-1 Masking the Detection Areas using Masking Plates

The near area mirror mounted in the main unit has 2 near masking plates; one at the right side of this mirror and another at the left side of this mirror. You can mask the detection area by changing the position of these masking plates.

Cautions>>

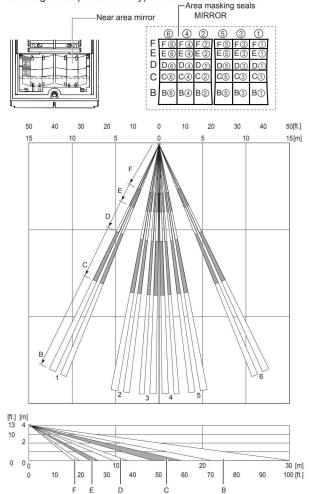
You can mask the outside detection areas only; they are areas 1 and 6. Use the area masking seals (an accessory) to mask the other detection areas (see Step 8-2).



8-2 Masking the Detection Areas using Masking Seals

Using the tweezers (an accessory), carefully attach the area masking seals (an accessory) to the near area mirror.

—Area masking seals



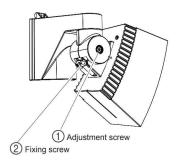
Points>>

If you are using the SIP-3020WF, SIP-4010WF, or SIP-404WF sensor unit when you have completed Step 8, proceed to Step 9.

9 TERMINATION PROCEDURE

Applicable models SIP-3020WF SIP-4010WF SIP-404WF

(1) After you have adjusted all sensor items, securely tighten all adjustment screws that you have loosened. Finally, securely tighten the bottom fixing screws.



Cautions>>

- If you need to adjust the detection area again, be sure to loosen the fixing screw. If you try to move the main unit without loosening the fixing screw, the unit may be damaged.
- When you mount the cover, place the excessive nylon wire loop in the main unit. If the wire has been pinched by the window and the cover, rain drops may be able to enter into the main unit.
- (2) Mount the cover.

10 OPERATION TEST

10-1 If There is a Public Street Where a People Walk or Cars Drive by the Detection Area

Points>>

Reduce the size of the detection area so that it does not include any public streets.

- (1) Check to see that the arrow of the main unit is within the width of "Angle adjustment guide" on the adjustment screw.
- (2) Using the area viewfinder, check to see that the detection area does not include any public streets.
- (3) If the detection area does go beyond a public street, correct the vertical angle of the main unit. However, exercise care so that the arrow does not move away significantly from the "Angle adjustment guide" position.

If the arrow does move away significantly from the "Angle adjustment guide" position:

Mask the far area detection area using the masking plate or by using the far area masking switch. You may be required to also mask the near area detection area under specific sensor installation conditions (see Steps 5 and 8).

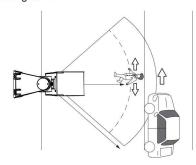
(4) When a person walks along the street or a car drives along it, check the detection area using the walk tester.

Points>>

You cannot mount and use both the area viewfinder and walk tester simultaneously.

Cautions>>

The detection area may increase if there is a large difference in temperature between the moving object and the background.



Cautions>>

A heat source beyond the detection area may cause a false alarm due to the reflection of heat off the ground. Examples of types of surfaces that reflect include water (puddles), wet roads, smooth concrete surfaces and asphalt roads.

If the source of the heat is strong and/or the reflection rate is high, the detection distance will be longer than required and may detect unnecessary objects beyond the target area. Therefore, select the detection range position according to the ground conditions of the installation site.



10-2 If Tree Branches or Grass are Detected When They Move Within the Detection Area

Points>>

Adjust the detection area so that it does not cover tree branches or grass that move when the wind blows.

- Check to see that the arrow of the main unit is within the width of "Angle adjustment guide" on the adjustment screw.
- (2) Using the area viewfinder, check to see that the detection area does not cover tree branches or grass that may move when the wind blows.
- (3) Use the walk tester to listen for sound level changes when there is no apparent activity in the detection area. Adjust the detection area so that it does not detect unwanted areas.

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If the sound level changes, some part of the detection area must be active (i.e.: an object is moving).

- (4) Use the walk tester and locate the part of the detection area that is active. Change the walk tester selector switch position and determine whether the active part of the detection area is far or near.
- (5) Using the area viewfinder again, locate the active detection area.
- (6) Mask the active detection area. To do this, mask the area using the masking plate or the masking seal. Otherwise mask the area using the far area masking switch (see Steps 5, 7, and 8).
- (7) Using the walk tester again, check that the sound level changes. If the sound level does not change excessively, you can finish the adjustment.

Points>>

You cannot mount and use both the area viewfinder and the walk tester simultaneously.

11 LED FUNCTIONS



Operation indicator - Red LED

Cautions>>

If the red LED keeps blinking for approx. 120 seconds after turning the power on, turn the power off and then on again.

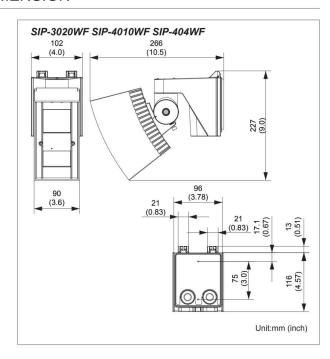
DETECTOR STATUS	If the cover is removed	
During power ON	Blinks.	
During standby	Turns OFF.	
When detected (in far/near area)	Lights.	

12 SPECIFICATIONS

12-1 Specifications of the Main Unit

Applicable models SIP-	3020WF SI	P-4010WF	SIP-404WF	
Model	SIP-3020WF	SIP-4010WF	SIP-404WF	
Detection method	Passive infrared			
Coverage	30 x 20m (100 x 65ft.)	40 x 10m (130 x 33ft.)	40 x 4m (130 x 13ft.)	
Number of detection zones	74 zones	48 zones	24 zones	
Mounting height	2.3	to 4m (7.6 to 1	3ft.)	
Power input	Alkali	3 - 9V DC ne or lithium b	attery	
Operating voltage		2.5 - 10V DC		
Current draw		l0 μA (standby x. (operating, l		
Operation indicator		RED ALARM		
Warm-up period	А	Approx. 120 sec.		
Detection range selector	Far area: ON / OFF			
Alarm interval period	0 / 5 / 60 / 150 sec.			
Detection logic selector	AND/OR			
Tamper output	N.C. 10V DC, 0.01A max.			
Trouble output	N.C. 10V DC, 0.01A max.			
Alarm output	N.C. 10V DC, 0.01A max. N.O. 10V DC, 0.01A max.			
Sensitivity selector	Far: SH/H/M/L Near: SH/H/M/L			
Operating temperature	-25 to +60°C (-13 to +140°F)			
IP rating	Main unit: IP65 Chassis: IP55			
Dimensions (H × W × D)	227 x 102 x 266mm (9 x 4 x 10.5 in.)			
Weight	1.2kg (42 oz.)			
Accessories	Screws, paper template, allen key, area masking seal, tweezers, instruction manual, area plate, fixing rubber form, cable glands			

DIMENSION



OPTION

• OPM-WT -Audio Walk Tester • AVF-1 -Area View Finder SIP-MINIHOOD -Sun/Snow shield

These units are designed to detect movement to activate CCTV system. Being only part of a complete surveillance system, we cannot accept responsibility for any damage or other consequences resulting form the activation of the unit. This product confirms the EMC Directive 2004/108/EC.

Specifications and design are subject to change without prior notice.



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